## LINEAR PNEUMATIC ACTUATORS

( $100 \mathrm{~cm}^{2}$ to $2400 \mathrm{~cm}^{2}$ )
DESCRIPTION
PA series pneumatic multi-spring actuators with rolling diaphragm, offering decreased hysterisis and good linearity throughout the operating range. Available in air to close and air to open versions, for modulating and on/off services.

MAIN FEATURES
Multi-spring compact design.
Actuators with roling diaphragm.
High spring thrusts and stroking speeds
Strokes up to 60 mm .
Sizes from $100 \mathrm{~cm}^{2}$ to $2400 \mathrm{~cm}^{2}$
Yoke and stem coupling with mounting according to NAMUR (DIN EC 60534-6-1).
Operation temperature range from $-20^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$.
OPTIONS AND
ACCESSORIES:
Stroke limiter
Stainless stee con
Positioners, limit switches, I/P converters, volume boosters, feedback units and others.

USE:
Actuation of ADCATrol control valves, or others on request.
AVAILABLE
MODELS:
PA10, PA25, PA40, PA80, PA80D and PA80T mild steel.
PA10i, PA25i and PA40i - stainless steal


| SPRING RANGES AND ACTUATOR THRUSTS |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ACTUATOR <br> MODEL | $\begin{array}{\|c\|} \hline \text { DIAPHRAGM } \\ \text { AREA } \\ \left(\mathrm{cm}^{2}\right) \end{array}$ | RATEDSTROKE (mm) | SPRING RANGE (bar) | SPRING | SPRING 0 mm travel (N) |  | ACTUATOR FORCE (N) IN RELATION TO MOTIVE AIR PRESSURE (bar) |  |  |  |  |  |  | $\begin{array}{\|c} \text { MAX. AR } \\ \text { SUPPLY } \end{array}$(bar) |
|  |  |  |  |  |  |  | 1,4 | 2 | 3 | 3,5 | 4 | 5 | 6 |  |
| PA10 | 100 | 20 | 0,2-1 a) | 1 | 200 | 1000 | 400 | 1000 | 2000 | 2500 | 3000 | 4000 | 5000 | 6 |
|  |  |  | 1-2 | 1 | 1000 | 2000 | - | - | 1000 | 1500 | 2000 | 3000 | 4000 |  |
|  |  |  | 2-4 | 1 | 2000 | 4000 | - | - | - |  |  | 1000 | 2000 |  |
| PA25 | 250 | 20 | 0,2-1 a) | 4 | 500 | 2500 | 1000 | 2500 | 5000 | 6250 | 7500 | 10000 | 12500 |  |
|  |  |  | 0,4-2 a) | 8 | 1000 | 5000 | - | - | 2500 | 3750 | 5000 | 7500 | 10000 |  |
|  |  |  | 1-2 | 4 | 2500 | 5000 | - | - | 2500 | 3750 | 5000 | 7500 | 10000 |  |
|  |  |  | 1,5-3 | 6 | 3750 | 7500 | - | - | - | 1250 | 2500 | 5000 | 7500 |  |
|  |  |  | 2-4 | 8 | 5000 | 10000 | - | - | - | - |  | 2500 | 5000 |  |
| PA40 | 400 | 30 | 0,2-1 a) | 4 | 800 | 4000 | 1600 | 4000 | 8000 | 10000 | 12000 | 16000 | 20000 |  |
|  |  |  | 0,4-2 a) | 8 | 1600 | 8000 | - | - | 4000 | 6000 | 8000 | 12000 | 16000 |  |
|  |  |  | 1-2 | 4 | 4000 | 8000 | - | - | 4000 | 6000 | 8000 | 12000 | 16000 |  |
|  |  |  | 1,5-3 | 6 | 6000 | 12000 | - | - | - | 2000 | 4000 | 8000 | 12000 |  |
|  |  |  | 2-4 | 8 | 8000 | 16000 | - | - | - | - | - | 4000 | 8000 |  |
| PA80 | 800 | $\begin{aligned} & 30 \\ & 60 \end{aligned}$ | 0,2-1 a) | 4 | 1600 | 8000 | 3200 | 8000 | 16000 | 20000 | 24000 | 32000 | 40000 |  |
|  |  |  | 0,4-2 a) | 8 | 3200 | 16000 | - | - | 8000 | 12000 | 16000 | 24000 | 32000 |  |
|  |  |  | 1-2 | 4 | 8000 | 16000 | - | - | 8000 | 12000 | 16000 | 24000 | 32000 |  |
|  |  |  | 1,5-3 | 6 | 12000 | 24000 | - | - | - | 4000 | 8000 | 16000 | 24000 |  |
|  |  |  | 2-4 | 8 | 16000 | 32000 | - | - | - | - | - | 8000 | 16000 |  |
| PA80D | 1600 | 60 | 0,2-1 a) | 8 | 3200 | 16000 | 6400 | 16000 | 32000 | 40000 | 48000 | 64000 | 80000 |  |
|  |  |  | 0,4-2 a) | 16 | 6400 | 32000 | - | - | 16000 | 24000 | 32000 | 48000 | 64000 |  |
|  |  |  | 1-2 | 8 | 16000 | 32000 | - | - | 16000 | 24000 | 32000 | 48000 | 64000 |  |
|  |  |  | 1,5-3 | 12 | 24000 | 48000 | - | - | - | 8000 | 16000 | 32000 | 48000 |  |
|  |  |  | 2-4 | 16 | 32000 | 64000 | - | - | - | - | - | 16000 | 32000 |  |
| $\underset{\text { ba })}{\substack{\text { bA }}}$ | 2400 | 60 | 0,2-1 a) | 12 | 4800 | 24000 | 9600 | 24000 | 48000 | 60000 | 72000 | 96000 | 120000 |  |
|  |  |  | 0,4-2 a) | 24 | 9600 | 48000 | - | - | 24000 | 36000 | 48000 | 72000 | 96000 |  |
|  |  |  | 1-2 | 12 | 24000 | 48000 | - | - | 24000 | 36000 | 48000 | 72000 | 96000 |  |
|  |  |  | 1,5-3 | 18 | 36000 | 72000 | - | - | - | 12000 | 24000 | 48000 | 72000 |  |
|  |  |  | 2-4 | 24 | 48000 | 96000 | - | - | - | - | - | 24000 | 48000 |  |

a) Actuator with $25 \%$ additional possible spring compression, allowing setting of $0,4-1,2$ bar $(0,2-1$ bar) and $0,8-2,4(0,4-2$ bar) operating ranges.

on valve stem thread. Can be course or fine thread. Other dimension the ADCATrol control valve model. Refer to its corresponding in Remarks: Stem coupling, yoke dimensions


| dimensions (mm) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | øA | B | c | D | E | øF | øG | H | 1 | M * | M1 | WEIGHT <br> (kg) |
| PA10 | 170 | 251 | 135 | 55 | 90 | 40,5 | 22 | 15 | G1/4" | M10 $\times 1$ | M10 | 6,3 |
| PA25 | 250 | 260 | 135 | 55 | 90 | 40,5 | 22 | 15 | G1/4" | M10 $\times 1$ | M10 | 10,1 |
| PA40 | 300 | 325/360 | 160/195 | 68 | 100 / 110 | 40,5/45 | 22 | 15 | G1/4" | $\begin{aligned} & \text { M10 } \times 1 / \\ & \text { M16 } \times 1,5 \end{aligned}$ | M10 | 18,7/19,2 |

Depencing on valve stem thread. Can be course or fine thread. Other dimensions on request.
Remarks: Stem coupling, yoke dimensions and design may vary depending on the ADCATrol control valve model. Refer to its corresponding information sheet or consult the manufacturer.
Mild steel and stainless steel construction share the same dimensions.



* Depending on valve stem thread. Can be course or fine thread. Other dimensions on request.
Remarks: Stem coupling, yoke dimensions and design may vary depending on the ADCATrol control valve model. Refer to its corresponding Remarks: Stem coupling, yoke dimensions and
information sheet or consult the manufacturer.


Depending on valve stem thread. Can be course or fine thread. Other dimensions on equatrs
Remarks: Stem coupling, yoke dimensions and design may vary depending on the ADCATrol cent. Refer to its corresponding Reforks. Stem coupling, yoke dimensions ars


| MATERIALS - ACTUATOR WITH TOP MOUNTED HANDWHEEL |  |  |
| :---: | :---: | :---: |
| POS. $\mathbf{N}^{\circ}$ | DESIGNATION | MATERIAL |
| $\mathbf{4 7}$ | Nut | AISI 316/1.4401 |
| $\mathbf{4 8}$ | Nut | AISI 316/1.4401 |
| $\mathbf{4 9}$ | Plain bearing | Steel / PTFE |
| $\mathbf{5 0}$ | Washer | Zinc plated steel |
| $\mathbf{5 1}$ | Bolt | AISI 304/1.4301 |
| $\mathbf{5 2}$ | Stem | AISI 316/1.4401 |
| $\mathbf{5 3}$ | Spindle | AISI 304/1.4301 |
| $\mathbf{5 4}$ | Handwheel | Steel |
| $\mathbf{5 5}$ | Washer | Zinc plated steel |
| $\mathbf{5 6}$ | Locknut | C45E/1.1191 |
| $\mathbf{5 7}$ | Nut | AISI 304/1.4301 |

## MATERIALS


PA10




| MATERIALS |  |  |  |
| :---: | :---: | :---: | :---: |
| POS. No | designation | PA10, PA25 and PA40 | PA10i, PA25i and PA40i |
| 1 | Lower actuator flange | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 |
| 2 | Yoke columns | C45E/1.1191 | AISI 304 / 1.4301 |
| 3 | Upper actuator flange | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 |
| 4 | Lower actuator cover | DD13/1.0335 | AISI $304 / 1.4301$ |
| 5 | Washers | Zinc plated steel | Zinc plated steel |
| 5A | Gasket | NBR | NBR |
| 6 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 6 A | Bolts | - | - |
| 7 | Actuator stem | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 8 | * O-ring | NBR | NBR |
| 10 | * O-ring | NBR | NBR |
| 11 | * Plain bearing | Steel / PTFE | Steel/PTFE |
| 12 | * Seal ring | Polyurethane | Polyurethane |
| 13 | Diaphragm plate | DD13/1.0335 | DD13/1.0335 |
| 14 | * Diaphragm | Reinforced NBR | Reinforced NBR |
| 15 | Diaphragm disk | C45E / 1.1191 | C45E / 1.1191 |
| 16 | Spring guide | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 17 | * Springs | Spring steel | Spring steel |
| 19 | Spacer | AISI 316 / 1.4401 | AISI 312 / 1.4401 |
| 21 | Nut | Zinc plated steel | Zinc plated steel |
| 24 | Upper actuator cover | DD13/1.0335 | AISI 304 / 1.4301 |
| 25 | Nuts | Zinc plated steel | Stainless steel A2-70 |
| 25A | Washers | Zinc plated steel | Stainless steel A2-70 |
| 26 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 27 | Coupling / Travel indicator | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 |
| 28 | Adaptor | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 30 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 31 | Nuts | Zinc plated steel | Stainless steel A2-70 |
| 36 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 38 | Eyebolts | Zinc plated steel | AISI 304 / 1.4301 |
| 39 | Vent plug | Brass; Plastic | Brass; Plastic |
| 40 | Fitting | Zinc plated steel; Plastic | Zinc plated steel; Plastic |


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| :---: | :---: |


| MATERIALS |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| POS. ${ }^{\circ}$ | designation | PA80 | PA80D | PA80T |
| 1 | Lower actuator flange | S235JR / 1.0038 | S235JR / 1.0038 | S235JR / 1.0038 |
| 2 | Yoke columns | C45E / 1.1191 | C45E / 1.1191 | C45E / 1.1191 |
| 4 | Lower actuator cover | DD13/1.0335 | DD13/1.0335 | DD13/1.0335 |
| 7 | Actuator stem | AISI 316/1.4401 | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 8 | * O-ring | NBR | NBR | NBR |
| 9 | * O-ring | - | NBR | NBR |
| 10 | * O-ring | NBR | NBR | NBR |
| 11 | * Plain bearing | Steel/PTFE | Steel / PTFE | Steel/PTFE |
| 12 | * Seal ring | Polyurethane | Polyurethane | Polyurethane |
| 13 | Diaphragm plate | DD13/1.0335 | DD13/1.0335 | DD13/1.0335 |
| 14 | * Diaphragm | Reinforced NBR | Reinforced NBR | Reinforced NBR |
| 15 | Diaphragm disk | S355JR / 1.0045 | S355JR / 1.0045 | S355JR / 1.0045 |
| 16 | Spring guide | DC01/1.0330 | DC01/1.0330 | DC01/1.0330 |
| 17 | * Springs | Spring steel | Spring steel | Spring steel |
| 18 | Intermediate actuator stem | - | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 19 | Spacer | AISI 316/1.4401 | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 20 | Spacer | AISI 316 / 1.4401 | - | - |
| 21 | Nut | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 22 | Intermediate cover | - | DD13/1.0335 | DD13/1.0335 |
| 24 | Upper actuator cover | DD13/1.0335 | DD13/1.0335 | DD13/1.0335 |
| 25 | Nuts | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 25A | Washers | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 26 | Bolts | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 27 | Coupling / Travel indicator | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 |
| 28 | Adaptor | AISI $304 / 1.4301$ | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 29 | Coupling flange | AISI $304 / 1.4301$ | AISI $304 / 1.4301$ | AISI 304 / 1.4301 |
| 30 | Bolts | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 31A | Nut | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 32 | * Stem guide | AISI 316L / 1.4404 | AISI 316L / 1.4404 | AISI 316L / 1.4404 |
| 33 | Intermediate stem guide | - | AISI 316L / 1.4404 | AIS 316L / 1.4404 |
| 34 | * Belleville washer | Spring steel | Spring steel | Spring steel |
| 35 | Stem guide lock nut | C45E / 1.1191 | C45E / 1.1191 | C45E / 1.1191 |
| 37 | Nuts | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 38 | Eyebolts | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 39 | Vent plug | Brass; Plastic | Brass; Plastic | Brass; Plastic |
| 40 | Fitting | Zinc plated steel | Zinc plated steel | Zinc plated steel |
| 41 | Compression fitting | - | Zinc plated steel | Zinc plated steel |
| 42 | Tube | - | AISI $304 / 1.4301$ | AISI 304 / 1.4301 |





Nosco
a) Not every spring range/stroke combination is available for each actuator model
b) Not avaiable in actuators with stainless steel construction (e.g. PA10

How to size: For selection of suitable actuator to use with ADCATrol control valves, consult IS PV15.00 - Maximum permissible pressure drops for ADCATrol control valves - or consult the manufacturer.

PA series pneumatic multi-spring actuators with rolling diaphragm, offering decreased hysterisis and good linearity throughout the operating range. Available in air to close and air to open versions, for modulating and on/off services.

MAIN FEATURES
Multi-spring compact design
Actuators with rolling diaphragm
High spring thrusts and stroking speeds
Strokes up to 30 mm .
Sizes from $140 \mathrm{~cm}^{2}$ to $700 \mathrm{~cm}^{2}$
Yoke and stem coupling with mounting according to NAMUR (DIN EC 60534-6-1)
Operation temperature range from $-20^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$.

OPTIONSAND
ACCESSORIES:
Stroke limit
Stainless steel construction
Positioners, limit switches, I/P converters, volume boosters, feedback units and others.

USE
AVAILABLE
MODELS:
Actuation of ADCATrol control valves, or others on request.
PA206, PA281, PA341 and PA436 - mild steel. PA206i, PA281i, PA341i and PA436i - stainless steel.
or other models, please consult IS PV3.70 - PA
LINEAR PNEUMATIC ACTUATORS
PA206, PA281, PA341 and PA436 ( $140 \mathrm{~cm}^{2}$ to $700 \mathrm{~cm}^{2}$ )

## DESCRIPTION

near pneumatic actuators.


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| SPRING RANGES AND ACTUATOR THRUSTS |  |  |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ACTUATOR <br> MODEL | $\underset{\substack{\text { DIAPHRAGM } \\\left(\mathrm{cm}^{2}\right)}}{\text { In }}$ (cm ${ }^{2}$ | RATEDSTROKE (mm) | $\begin{aligned} & \text { SPRING } \\ & \text { RANGE } \\ & \text { (harl } \end{aligned}$(bar) | SPRING | SPRINGFORCEAT 0 mm TRAVEL (N) | SPRINGFORCE AT RATED TRAVEL (N) | ACTUATOR FORCE (N) IN RELATION TO MOTIVE AIR PRESSURE (bar) |  |  |  |  |  |  | $\underset{\text { SUPPLIL }}{\substack{\text { MAX. AIR }}}$ (bar) |
|  |  |  |  |  |  |  | 1,4 | 2 | 3 | 3,5 | 4 | 5 | 6 |  |
| PA206 | 140 | 20 | 0,2-1 a) | 1 | 280 | 1000 | 560 | 1400 | 2800 | 3500 | - | - | - | 3,5 |
|  |  |  | 1-3b) | 2 | 1400 | 4200 | - | - | - | 700 | - | - | - |  |
| PA281 | 300 | 20 | 0,2-1 a) | 4 | 600 | 3000 | 1200 | 3000 | 6000 | 7500 | - | - | - |  |
|  |  |  | 0,4-2 a) | 8 | 1200 | 6000 | - | - | 3000 | 4500 | - | - | - |  |
|  |  |  | 0,8-1,6 | 4 | 2400 | 4200 | - | 1200 | 4200 | 5700 | - | - | - |  |
|  |  |  | 1,2-2,4 | 6 | 3600 | 7200 | - | - | 1800 | 3300 | - | - | - |  |
|  |  |  | 1,6-3,2 | 8 | 4800 | 9600 | - | - | - | 900 | - | - | - |  |
| PA341 | 445 | 30 | 0,2-1 a) | 4 | 890 | 4450 | 1780 | 4450 | 8900 | 11125 | - | - | - |  |
|  |  |  | 0,4-2 a) | 8 | 1780 | 8900 | - |  | 4450 | 6675 | - | - | - |  |
|  |  |  | 0,6-1,4 | 4 | 2670 | 6230 | - | 2670 | 7120 | 9345 | - | - | - |  |
|  |  |  | 0,9-2,1 | 6 | 4005 | 9345 | - | - | 4005 | 6230 | - | - | - |  |
|  |  |  | 1,2-2,8 | 8 | 5340 | 12460 | - | - | - | 3115 | - | - | - |  |
| PA436 | 700 | 30 | 0,2-1 a) | 4 | 1400 | 7000 | 2800 | 7000 | 14000 | 17500 | - | - | - |  |
|  |  |  | 0,4-2 a) | 8 | 2800 | 14000 | - | - | 7000 | 10500 | - | - | - |  |
|  |  |  | 1-2 | 4 | 7000 | 14000 | - | - | 7000 | 10500 | - | - | - |  |
|  |  |  | 1,5-3 | 6 | 10500 | 21000 | - | - |  | 3500 | - | - | - |  |
|  |  |  | 2-4 | 8 | 14000 | 28000 | - | - | - | - | - | 7000 | 14000 | 6 |
| a) Actuator with $25 \%$ additional possible spring compression, allowing setting of $0,4-1,2$ bar ( $0,2-1$ bar) and $0,8-2,4(0,4-2$ bar) operating ranges. <br> b) Not available in air to close, "stem retracts by spring force" version. |  |  |  |  |  |  |  |  |  |  |  |  |  |  |

a) Actuator with $25 \%$ additional possible spring compression, alowing s.
b) Not available in air to close, "stem retracts by spring force" version.


| dimensions (mm) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | øA | B | c | D | E | øF | øG | H | 1 | M * | M1 | $\underset{(\mathrm{kg})}{\text { WEIGT }}$ |
| PA206 | 209 | 236 | 135 | 55 | 110 | 40 | 22 | 15 | G 1/4" | M10 $\times 1$ | M10 | 6,5 |
| PA281 | 275 | 243 | 135 | 55 | 110 | 40 | 22 | 15 | G 1/4" | M10 $\times 1$ | M10 | 10 |
| PA341 | 336 | 288/323 | 160 / 195 | 68 | 110 | 45 | 22 | 15 | G 1/4" | M10 $\times 1 / \mathrm{M} 16 \times 1,5$ | M10 | 16 |
| PA436 | 430 | $\begin{array}{\|c\|} \hline 316 / 351 \\ 336 / 371 * * \\ \hline \end{array}$ | 160/195 | 68 | 110 | 45 | 22 | 15 | G 1/4" | M10 $\times 1$ / M16 x 1,5 | M10 | $\begin{gathered} 27 \\ 31 \\ 31 \end{gathered}$ |

*Depending on valve stem thread. Can be course or fine thread.
**Actuators with spring ranges $1-2$ bar, $1,5-3$ bar and $2-4$ bar.
** Actuators with spring ranges $1-2$ bar, $1,5-3$ bar and $2-4$ bar.
Remarks: Stem coupling, yoke dimensions and design may vary depending on the ADCATrol control valve model. Refer to its corresponding Remarks: Stem coupling, yoke dimensions and design may vary dep
information sheet or consult the manufucature.
Mild steel and stainless steel construction share the same dimensions.


DIMENSIONS - ACTUATOR WITH TOP MOUNTED HANDWHEEL (mm)

| MODEL | ØN | L |
| :---: | :---: | :---: |
| PA206 | 250 | 106 |
| PA281 | 250 | 106 |
| PA341 | 300 | 111 |
| PA436 | 400 | 156 |

MATERIALS


| MATERIALS |  |  |  |
| :---: | :---: | :---: | :---: |
| POS. No | designation | PA206, PA281, PA341 and PA436 | PA206i, PA281i, PA341i and PA436i |
| 1 | Lower actuator flange | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 |
| 2 | Yoke columns | C45E / 1.1191 | AISI 304 / 1.4301 |
| 3 | Upper actuator flange | C45E / 1.1191 | A351 CF8 / 1.4308; AISI 304 / 1.4301 |
| 4 | Lower actuator cover | DD12/1.0398 | AISI 304 / 1.4301 |
| 5 | Washers | Zinc plated steel | Zinc plated steel |
| 6 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 7 | Actuator stem | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 8 | * O-ring | NBR | NBR |
| 11 | * Plain bearing | Steel/PTFE | Steel / PTFE |
| 12 | * Seal ring | Polyurethane | Polyurethane |
| 13 | Diaphragm plate | S235JR/1.0038 | S235JR/1.0038 |
| 14 | * Diaphragm | Reinforced NBR | Reinforced NBR |
| 15 | Diaphragm disk | C45E / 1.1191 | C45E / 1.1191 |
| 16 | Spring guide | C45E / 1.1191 | C45E / 1.1191 |
| 17 | * Springs | Spring steel | Spring steel |
| 19 | Spacer | C45E / 1.1191 | C45E / 1.1191 |
| 21 | Nut | Zinc plated steel | Zinc plated steel |
| 23 | Cover spacer | Aluminium | Aluminium |
| 24 | Upper actuator cover | DD12/1.0398 | AISI 304 / 1.4301 |
| 25 | Nuts | Zinc plated steel | Stainless steel A2-70 |
| 25A | Washers | Zinc plated steel | Stainless steel A2-70 |
| 26 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 27 | Coupling / Travel indicator | A351 CF8 / 1.4308 | A351 CF8 / 1.4308 |
| 28 | Adaptor | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 30 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 31 | Nuts | Zinc plated steel | Stainless steel A2-70 |
| 32 | * Stem guide | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 36 | Bolts | Zinc plated steel | Stainless steel A2-70 |
| 38 | Eyebolts | Zinc plated steel | AISI 304 / 1.4301 |
| 39 | Vent plug | Brass; Plastic | Brass; Plastic |
| 40 | Fitting | Zinc plated steel; Plastic | Zinc plated steel; Plastic |
| 47 | Nut | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 48 | Nut | AISI 316/1.4401 | AISI 316/1.4401 |
| 49 | Plain bearing | Steel/ PTFE | Steel / PTFE |
| 50 | Washer | Zinc plated steel | Zinc plated steel |
| 51 | Bolt | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 52 | Stem | AISI 316 / 1.4401 | AISI 316 / 1.4401 |
| 53 | Spindle | AISI 304 / 1.4301 | AISI 304 / 1.4301 |
| 54 | Handwheel | Steel | Steel |
| 55 | Washer | Zinc plated steel | Zinc plated steel |
| 56 | Locknut | C45E / 1.1191 | C45E / 1.1191 |
| 57 | Nut | AISI 304 / 1.4301 | AISI 304 / 1.4301 |




Full description or additional codes have to be added in case of a non-standard combination
a) Not every spring range/stroke combination is available for each actuator model
c) Exact model and size must be specified - consult the manufacturer

How to size: For selection of suitable actuator to use with ADCATrol control valves, consult IS PV15.00 - Maximum permissible pressure drops for ADCATrol control valves - or consult the manufacturer.

## LINEAR ELECTRIC ACTUATORS

EL

## ( $1,2 \mathrm{kN}$ to 25 kN )

## DESCRIPTION

The EL series linear electric actuators are designed for operation of control valves in modulating and on/off services in process engineering and industrial applications. The self-locking stem nut is driven by an lectric motor via a gearing.
oad-dependent switches and/or mechanical limit switches define the tops for the end positions.

MAIN FEATURES
Modular retrofittable design.
$24 \mathrm{VAC}, 115 \vee \mathrm{AC}, 230 \vee \mathrm{AC}, 400 \vee \mathrm{AC} 50 / 60 \mathrm{~Hz}$ and $24 \vee \mathrm{DC}$ supply voltages.
Manual operation with disengagement of the actuator motor
P 65 (EL12 IP 43) protection.
Valve protection against excessive force due to load-dependent seating.
Mounting to valves made via yoke or mounting flange DIN 3358 , enabling easy connection to all types of valves. Standard version is suitable for ADCATrol valves
Defined closing force in the end positions leading to tight valve shutoff.
tall proof synchronous motors (or brake motors for higher positioning rces) ensure highest positioning accuracy.

Exact, backlash-free measurement of actual valve stroke by direct coupling to the valve stem.
Universally usable actuators due to control via 3-point-step controllers, analogue input signals ( 0 to $10 \mathrm{~V}, 0(4)$ to 20 mA ), or fieldbus systems. Limit switches are easily adjustable for stroke limitation or as signal or intermediate positions.
OPTIONS AND
ACCESSORIES: Electronic positioner.
Additional limit switches.
Potentiometers e.g. for 3-point-step control in closed loop.
0 (4) to 20 mA electronic position feedback units. Heating resistor.
Special coatings and finishes for aggressive environments.

USE:
AVAILABLE
MODELS:

Actuation of
EL12, EL20, EL45, EL80, EL120 and EL250.

## TECHNICAL DATA

| MODEL | EL12 | EL20 | EL45 |  | EL45.1 | EL45.2 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Positioning force (kN) | 1,2 | 2,0 | 4,5 |  | 4,5 | 4,5 |
| Positioning speed ( $\mathrm{mm} / \mathrm{min} / \mathrm{mm} / \mathrm{s}$ ) a) | 8/0,14 | 15/0,25 | 17/0,28 |  | 25/0,4 | 50/0,8 |
| Power consumption - 230 V (W) | 4 | 6,6 | 28 |  | 28 | 32 |
| Nominal current - 230 V (A) | 0,017 | 0,029 | 0,135 |  | 0,135 | 0,160 |
| Type of motor b) | Syn | Syn | Asyn |  | Asyn | Asyn |
| Motor protection c) | B ${ }^{\text {B }}$ |  |  |  |  |  |
| Maximum stroke (mm) | 35 | 50 (75 on request) |  |  |  |  |
| Supply voltages d) | $24 \mathrm{~V} / 115 \mathrm{~V} / 230 \mathrm{~V} / 400 \mathrm{~V} 50 / 60 \mathrm{~Hz}, 24 \mathrm{VDC}$ |  |  |  |  |  |
| Type of duty acc. to IEC 34-1 | S1-100\% |  | S4-30\% c.d.f. 600 ch |  |  |  |
| Cable entry | $3 \times \mathrm{M16} \mathrm{\times 1,5}$ | $2 \times \mathrm{M} 16 \times 1,5$ and 1 dummy plug M16 $\times 1,5$ |  |  |  |  |
| Electrical connection | Inside terminal board, terminal configuration according to electric connection wiring diagram |  |  |  |  |  |
| Switch off in end position | 2 load dependent switches, max. 250 VAC , rating for resistive load: max. 5 A , for inductive load: max. 3 A |  |  |  |  |  |
| Mounting position | As desired, except downward position |  |  |  |  |  |
| Ambient temperature | $-20^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Lubricant for gearing | Klüber Mickrolube GL 261 grease |  |  |  |  |  |
| Position indicator | By anti-rotation bar |  |  |  |  |  |
| Manual adjustment | Crank handle | Side handwheel |  |  |  |  |
| Enclosure protection acc. to EN 60529 | IP 43 | IP 65 |  |  |  |  |
| Trapezoidal thread | Tr $8 \times 1,5$ | Tr $14 \times 3$ |  |  |  |  |
| Connection type | EN ISO 5210 F05 |  |  |  |  |  |
|  |  |  |  |  |  |  |
| MODEL | EL80 | EL80.1 | EL80.2 | EL120 | EL120. 1 | EL120.2 |
| Positioning force (kN) | 8,0 |  |  | 12 |  |  |
| Positioning speed ( $\mathrm{mm} / \mathrm{min} / \mathrm{mm} / \mathrm{s}$ ) a) | 13,5/0,2 | 25/0,4 | 50/0,8 | 13,5 / 0,2 | 25/0,4 | 50/0,8 |
| Power consumption - 230 V ( W ) | 25 | 34 | 152 | 25 | 34 | 152 |
| Nominal current - 230 V (A) | 0,11 | 0,15 | 0,78 | 0,11 | 0,15 | 0,78 |
| Type of motor b) | Syn | Syn | Asyn | Syn | Syn | Asyn |
| Motor protection c) | B | B | T | B | B | T |
| Maximum stroke (mm) | 80 |  |  |  |  |  |
| Supply voltages d) | $24 \mathrm{~V} / 115 \mathrm{~V} / 230 \mathrm{~V} / 400 \mathrm{~V} 50 / 60 \mathrm{~Hz}, 24 \mathrm{VDC}$ |  |  |  |  |  |
| Type of duty acc. to IEC 34-1 | S4-30\% c.d.f. 600 ch |  |  |  |  |  |
| Cable entry | $2 \times \mathrm{M} 16 \times 1,5$ and 1 dummy plug M16 $\times 1,5$ |  |  |  |  |  |
| Electrical connection | Inside terminal board, terminal configuration according to electric connection wiring diagram |  |  |  |  |  |
| Switch off in end position | 2 load dependent switches, max. 250 V AC , rating for resistive load: max. 5 A , for inductive load: max. 3 A |  |  |  |  |  |
| Mounting position | As desired, except downward position |  |  |  |  |  |
| Ambient temperature | $-20^{\circ} \mathrm{C}$ to $60^{\circ} \mathrm{C}$ |  |  |  |  |  |
| Lubricant for gearing | Klüber Mickrolube GL 261 grease |  |  |  |  |  |
| Position indicator | By anti-rotation bar |  |  |  |  |  |
| Manual adjustment | Side handwheel |  |  |  |  |  |
| Enclosure protection acc. to EN 60529 | IP65 |  |  |  |  |  |
| Trapezoidal thread | Tr $20 \times 3$ |  |  |  |  |  |
| Connection type | DIN 3210 G0 |  |  |  |  |  |



## Tonection type

at 60 Hz the positioning speed and input power increase by $20 \%$
b) Syn - synchronous motor; Asyn - asynchronous motor.
d) Other supply voltages on request.

| OPTIONS AND ACCESSORIES |  |
| :---: | :---: |
| designation | DESCRIPTION |
| FG | Switching and signaling unit (teletransmitter assembly). The FG unit is the base necessary for the assembly of all remaining options. |
| WE | Additional limit switches for signaling end positions or intermediate positions, freely adjustable, max. 250 V AC , rating for resistive load max. 5 A, for inductive load max. 3 A , max. 2 switches for EL20 and EL45, max. 4 switches for EL80 and EL120. |
| WE-G | Additional limit switches for signaling end positions or intermediate positions, freely adjustable, with gold-plated contacts for low voltage, max. 30 VAC , rating for resistive load max. 0,1 A, max. 2 switches for EL20 and EL45, max. 4 switches for EL80 and EL120 |
| POT | Potentiometer 100/130/200/500/1000/5000 Ohms or 10 kOhms Linearity error $£ 0.5 \%$, max. 1.5 W , contact current 30 mA max. 2 pieces |
| ESR100 | Electronic position feedback 2/3-wire unit. Remark: Includes POT 5000 Ohms. Inductive travel measuring, output 0(4) to 20 mA . <br> Connection 24 V DC (not possible for EL12). |
| PEL100 | Electronic positioner for actuator control. Remark: Includes FG teletransmitter assembly and POT 1000 Ohms. Input 0 to $10 \mathrm{~V}, 0(4)$ to 20 , output 0 to $10 \mathrm{~V}, 0(4)$ to 20 mA . <br> Supply voltage $24,115,230 \mathrm{~V} 50 / 60 \mathrm{~Hz}$. |
| PEL200 | Intelligent electronic positioner for actuator control. Remark: Includes FG teletransmitter assembly and POT 1000 Ohms. Input 0 to $10 \mathrm{~V}, 0(4)$ to 20 mA , output 0 to $10 \mathrm{~V}, 0(4)$ to 20 mA . <br> Supply voltage $24,115,230 \mathrm{~V} 50 / 60 \mathrm{~Hz}$. |
| HZWP | Heating resistor with thermoswitch against moisture with automatic temperature regulation, max. 15 Watts Supply voltage $24,115,230 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |
| STALA/ FLA | Yoke for adaptation to valves. Refer to dimension sheet. |
| zFLA | Mounting flange with central attachment Mxx. Refer to dimensions sheet (thrust rod must be secured against revolving). |
| ks | Compact plug 10/24 poles with additional housing at actuator voltages $\leq 500 \mathrm{~V}$. |
| LA-TR | Special finish coating for use in the tropics ("rropics coating"). |
| A-IP65 | Version IP 65: with bellows at thrust rod and metal cover with seal (for EL12) |
| A-FAB | Version with bellows at thrust rod (for EL20, 45, 80 and 120). |



## 

HZ - Heater with thermoswitch
POT - Heater with the
ESR - Electronic position feedback
PEL-Electronic positioner
WSE - External reversing contactor unit

| model | $ø$ A | B | c | D | E | $\varnothing$ F | $\varnothing \mathrm{G}$ | H | 1 | M * | M1 | M2 | WGT. |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EL12 | 129 | 315 | 175 | - | 100 | 40 | 16 | 35 | - | M10 | M10 | - | 2,1 |
| EL20 / EL45 | 148 | 474 | 205 | 42 | 100/110 | 40/45 | 22 | 50 | 41 | M10 / M16 | M10 | M16 | 8 |
| EL80 / EL120 | 188 | 572 | 245 | 70 | 100/110 | 40/45 | 22 | 80 | 41 | M10 / M16 | M10 | M16 | 13 |
| EL250 | 216 | 668 | 260 | 70 | 125 | 45/65 | 22 | 100 | 41 | M16 / M20 | - | M16 | 19 |

* Depending on valve stem thread. Can be course or fine thread. information sheet or consult the manufacturer

a) Require an additional WE limit switch for switching off in the upper end position. Except V928MV, V928MH and V928D.
b) Exact model and size must be specified - consult the manufacturer.

Remark: Options and accessories not mentioned in the ordering codes table must be requested separately e.g.: E 201XXXA1 fitted with HZ/WP
heating resistor with thermoswitch.
How to size: For selection of suitable actuator to use with ADCATrol control valves, consult IS PV15.00 - Maximum permissible pressure drops for How to size: For selection of suitable actuator to use with
ADCATrol control valves - or consult the manufacturer.

## LINEAR ELECTRIC ACTUATORS WITH FAIL-SAFE FUNCTION

## ELR

## DESCRIPTION

The ELR series linear electric actuators are designed for operation of control valves in modulating and on/off services in process engineering and industrial applications. The self-locking stem nut is driven by an electric motor via a gearing
oad-dependent switches and/or mechanical limit switches define or
case the electric linear actuator runs into the espective fail-safe position by spring force (thrust rod either extended or retracted). In modulating
limit switches.
MAIN FEATURES
Modular retrofittable design
$24 \mathrm{~V} \mathrm{AC}, 115 \mathrm{~V}$ AC, $230 \vee \mathrm{AC}, 400 \mathrm{~V}$ AC $50 / 60 \mathrm{~Hz}$ and 24 V DC supply voltages.
Electric manual operation with OPEN/CLOSE buttons.
IP 54 protection.
Valve protection against excessive force due to load-dependent seating.
Mounting to valves made via yoke or mounting flange DIN 3358 , nabling easy connection to all types of valves. Standard version is suitable for ADCATrol valves
off.
Stall proof synchronous motors (or brake motors for higher positioning forces) ensure highest positioning accuracy.
Mechanical stroke indication via anti-rotation bar.
Exact, backlash-free measurement of actual valve stroke by direct oupling to the valve stem.
Universally usable actuators due to control via 3-point-step controllers, analogue input signals ( 0 to $10 \mathrm{~V}, 0(4)$ to 20 mA ), or fieldbus systems imit switches are easily adjustable for stroke limitation or as signal for intermediate positions.

## OPTIONS AND

ACCESSORIES:
Electronic positioner.
Additional limit switches.
Potentiometers e.g. for 3 -point-step control in closed loop.
0 (4) to 20 mA electronic position feedback units. Heating resistor.
Special coatings and finishes for aggressive environments.

Actuation of ADCATrol control valves, or others on request.

ELR2.1, ELR2.2 and ELR2.3

| MODEL | ELR 2.1 | ELR 2.2 | ELR 2.3 |
| :---: | :---: | :---: | :---: |
| Positioning force - CLOSED (KN) a) | $\geq 0,9$ | $\geq 2,2$ | $\geq 2,2$ |
| Positioning force - OPEN (kN) a) | $\leq 5,3$ | $\leq 4,0$ | $\leq 4,0$ |
| Maximum stroke (mm) | 35 | 35 | 46 |
| Positioning speed modulating duty ( $\mathrm{mm} / \mathrm{min} / \mathrm{mm} / \mathrm{s}$ ) b) | 17,5 / 0,29 |  |  |
| Positioning speed in case of power failure Fail-safe function (mm/s) | $\sim 4,1$ |  |  |
| Power consumption (230 V) motor ( W ) | 8,5 |  |  |
| Power consumption (230 V) magnet (W) | 15 |  |  |
| Type of motor c) | Syn |  |  |
| Motor protection d) | B |  |  |
| Supply voltages e) | $24 \mathrm{~V} / 115 \mathrm{~V} / 230 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |  |  |
| Closing direction (Fail-safe function) | Extending thrust rod or retracting thrust rod |  |  |
| Cable entry | $2 \times \mathrm{M} 16 \times 1,5$ and 2 dummy plugs M20 $\times 1,5$ |  |  |
| Type of duty acc. to IEC 34-1 | S1-100\% c.d.f., S4-30\% c.d.f. 1200 ch |  |  |
| Electrical connection | Inside terminal board, terminal configuration according to electrical connection wiring diagram |  |  |
| Switch off in end position | 2 limit switches, max. 250 V AC , <br> rating for resistive load, max. 10 A , for inductive load, max. 10 A |  |  |
| Mounting position | Any, except downward |  |  |
| Ambient temperature | $-20^{\circ} \mathrm{C}$ to $50^{\circ} \mathrm{C}$ |  |  |
| Lubricant for gearing | Renolit AL-WIK 260 X |  |  |
| Position indicator | By anti-rotation bar |  |  |
| Manual adjustment | Electrical adjustment via push buttons (only possible when voltage is present) |  |  |
| Enclosure protection acc. to EN 60529 | IP 54 |  |  |
| Connection type | EN ISO 5210 F05 (also refer to options) |  |  |
| Test / approvals | Actuator has been tested by TÜV (German Technical control board) according to DIN 32730 (safety functions for water and steam in heating systems) |  |  |

a) Force depends on valve stroke according to Chart 1 .
b) At 60 Hz , the positioning speeds and input power increase by $20 \%$.
c) Other supply voltages on request.
d) Syn- synchronous motor; Asyn - asynchronous motor
e) B - stall


Chart 1 - Closing force according to valve stroke.


| DIMENSIONS (mm) |  |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | $\square \mathrm{A}$ | B | c | E | ø F | $\varnothing \mathrm{G}$ | H | 1 | M * | M1 | M2 | WEIGHT (kg) |
| ELR2.1 | 162 | 497/515** | 170 | $100 / 110$ | 40/45 | 22 | 35 | 41 | M10 | M10 | M16 | 8,7 |
| ELR2. 2 | 162 | 518/555** | 170 | $100 / 110$ | 40/45 | 22 | 35 | 41 | M10 | M10 | M16 | 9,3 |
| ELR2.3 | 162 | 539/575** | 170 | 100/110 | 40/45 | 22 | 46 | 41 | M10 | M10 | M16 | 10 |

Depending on valve stem thread. Can be course or fine thread.
*With PEL electronic positioner
Remark: Stem coupling, yoke dimensions and design may vary depending on the ADCATrol control valve model. Refer to its corresponding information sheet or consult the manufacturer.

| ORDERING CODES ELR |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Group designation | E | 2A | 1 | x | x | x | A1 |  |
| EL series linear electric actuator | E |  |  |  |  |  |  |  |
| Actuator model |  |  |  |  |  |  |  |  |
| ELR2.1 |  | 2A |  |  |  |  |  |  |
| ELR2.2 |  | 2B |  |  |  |  |  |  |
| ELR2. 3 |  | 2 C |  |  |  |  |  |  |
| Supply voltage |  |  |  |  |  |  |  |  |
| $230 \mathrm{~V} \mathrm{AC} 50 / 60 \mathrm{~Hz}$ |  |  | 1 |  |  |  |  |  |
| $115 \mathrm{~V} \mathrm{AC} 50 / 60 \mathrm{~Hz}$ |  |  | 2 |  |  |  |  |  |
| 24 V AC 50/60 Hz |  |  | 3 |  |  |  |  |  |
| 24 V DC |  |  | 4 |  |  |  |  |  |
| $400 \mathrm{~V} \mathrm{AC} \mathrm{3} \mathrm{\sim} 0 / 60 \mathrm{~Hz}$ |  |  | 5 |  |  |  |  |  |
| Electronic positioner and teletransmitter assembly |  |  |  |  |  |  |  |  |
| Without FG teletransmitter assembly and electronic positioner |  |  |  | x |  |  |  |  |
| FG teletransmitter assembly |  |  |  | T |  |  |  |  |
| PEL100 electronic positioner |  |  |  | P |  |  |  |  |
| PEL200 intelligent electronic positioner |  |  |  | 1 |  |  |  |  |
| Limit switches |  |  |  |  |  |  |  |  |
| Without additional limit switches |  |  |  |  | x |  |  |  |
| One additional WE limit switch |  |  |  |  | 1 |  |  |  |
| Two additional WE limit switches |  |  |  |  | 2 |  |  |  |
| Position feedback unit |  |  |  |  |  |  |  |  |
| Without position feedback unit |  |  |  |  |  | x |  |  |
| ESR100 electronic position feedback unit |  |  |  |  |  | F |  |  |
| Yoke design and coupling |  |  |  |  |  |  |  |  |
| ADCATrol V16/2 and V25/2 series (DN 15 to DN $50-1 / 2^{\prime \prime}$ to $2^{\prime \prime}$ ) |  |  |  |  |  |  | A1 |  |
| ADCATrol V16/2 series (DN 65 to DN $100-3^{\prime \prime}$ to 4") |  |  |  |  |  |  | B1 |  |
| ADCATrol V25/2 series (DN 65 to DN $100-3^{\prime \prime}$ to 4") |  |  |  |  |  |  | B2 |  |
| ADCATrol V25/2 series (DN 125 to DN $150-5^{\prime \prime}$ to $6^{\prime \prime}$ ) |  |  |  |  |  |  | C2 |  |
| ADCATrol V25/2 series (DN $200-8{ }^{\prime \prime}$ ) |  |  |  |  |  |  | D2 |  |
| Other ADCATrol valves a) |  |  |  |  |  |  | xx |  |
| Special versions / Extras |  |  |  |  |  |  |  |  |
| Full description or additional codes have to be added in case of a non-standard combination |  |  |  |  |  |  |  | E |
| a) Exact model and size must be specified - consult the manufacturer. <br> Remark: Options and accessories not mentioned in the ordering codes table must be requested separately, e.g.: E.2A1TXXA1 with special LA-TR finish coating. <br> How to size: For selection of suitable actuator to use with ADCATrol control valves, consult IS PV15.00 - Maximum permissible pressure drops for ADCATrol control valves - or consult the manufacturer. |  |  |  |  |  |  |  |  |

## LINEAR ELECTRIC ACTUATORS

 AVF234S and AVM234S
## DESCRIPTION

The AVM234S / AVF234S valve actuators offer automatic adaptation to the stroke of the valve, precision activation and high energy efficiency with minimal operating noise.
deal for use with any DSH series direct steam injection humidifier and in TDS (Total Dissolved Solids) control systems VCP blowdown valves.
case of power failure/interruption, the AVF234S actuator runs, spring driven, into its respective fail-safe position (thrust rod extended). In modulating duty, the end position seating is made via limit switches. MAIN FEATURES
P 66 protection.
Automatic detection of control signal with LED indications
Adjustable characteristic curve (linear, quadratic and equalpercentage) and running time via DIP switch.
utomatic adaptation to valve stroke
Manual operation with disengagement of the actuator motor
Spring return feature (AVF234S).
Switching input (2-point or 3-point-step control) or analog input (0... 10 $V$ or $4 \ldots . .20 \mathrm{~mA}$ ).

OPTIONS AND
ACCESSORIES:
Spit-range unit for adjusting sequences
230 VAC and 100 V AC power supply modules.
Auxiliary change over contacts.
Potentiometers, e.g. for 3-point-step in closed loop.
Adapters for high temperature conditions.
USE:
AVAILABLE
MODELS:
Actuation of V series ADCATrol control valves, or others on request.

AVM234S.


AVF234S - Fail-safe with spring-return.

## TECHNICAL DATA

| ACTUATOR MODEL | AVM234S | AVF234S |
| :---: | :---: | :---: |
| Power supply | $230 \mathrm{~V} 50 / 60 \mathrm{~Hz} / 110 \mathrm{~V} 50 / 60 \mathrm{~Hz} / 24 \mathrm{~V} 50 / 60 \mathrm{~Hz} / 24 \mathrm{~V} \mathrm{DC}$ |  |
| Power consumption a) | $10 \mathrm{~W}(20 \mathrm{VA})$ for $24 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ and 24 V DC; $13 \mathrm{~W}(28 \mathrm{VA}$ ) for $230 \mathrm{~V} 50 / 60 \mathrm{~Hz}$ |  |
| Running time of motor mm/min (mm/s) | $10(0,17), 15(0,25), 30(0,50)$ |  |
| Running time of spring b) | - | $15 . . .30 \mathrm{~s}$ |
| Actuating power | 2,5 kN | 2 kN |
| Response time for 3-point-step | 200 ms |  |
| Number of spring returns | - | >40,000 |
| Actuator stroke | $0 \ldots .49 \mathrm{~mm}$ | 0... 40 mm |
| Housing material | Fire-retardant plastic |  |
| a) Choose transformer for this value, otherwise malfunctions may occur. <br> b) Return time equates to stroke of $14 \ldots 40 \mathrm{~mm}$ and does not depend on set running time. |  |  |
| POSITIONER |  |  |
| Control signal 1 | $0 . .10 \mathrm{~V}, \mathrm{Ri}=100 \mathrm{k} \Omega$ |  |
| Control signal 2 | $4 . . .20 \mathrm{~mA}, \mathrm{Ri}=50 \Omega$ |  |
| Positional feedback 0-10V | $0 . . .10 \mathrm{~V} ;$ load $>2,5 \mathrm{k} \Omega$ |  |
| Starting point U0 | 0 V or 10 V |  |
| Control span $\Delta \mathrm{U}$ | 10 V |  |
| Switching range Xsh | 300 mV |  |


| AMBIENT CONDITIONS |  |
| :--- | :---: |
| Admissible ambient temperature | $-10 \ldots 55^{\circ} \mathrm{C}$ |
| Admissible ambient humidity | $<95 \%$ rh, no condensation |
| Temperature of medium c) | Max. $130^{\circ} \mathrm{C}\left(180^{\circ} \mathrm{C}\right.$ or $200^{\circ} \mathrm{C}$ with accessories) |
| c) Adaptor needed for higher temperatures $\left(180^{\circ} \mathrm{C}\right.$ or $\left.200^{\circ} \mathrm{C}\right)($ see accessories and options $)$. |  |

c) Adaptor needed for higher temperatures $\left(180^{\circ} \mathrm{C}\right.$ or $200^{\circ} \mathrm{C}$ ) (see accessories and options).

| STANDARDS AND DIRECTIVES |  |
| :--- | :---: |
| Type of protection | IP66 (EN 60529) |
| Protection class | III (IEC 60730) |
| EMC Directive 2014/30/EU d) | EN 61000-6-2, EN 61000-6-4 |
| Low-voltage directive 2014/35/EU | EN 60730-1, EN 60730-2-14 |
| Over-voltage categories | III |
| Degree of contamination | III |
| d) EN 61000-6-2: HF immunity, limitation of feedback signal between 80 MHz and 1000 MHz criterion B, otherwise criterion A. |  |

$\triangle D C A$

| OPTIONS AND ACCESSORIES | TYPE |
| :--- | :---: |
| Split-range unit for adjusting sequences, fitted in separate junction box | 313529001 |
| Module for 2-point $/ 3$-point and analogue activation; additional power $2 \mathrm{VA} ; 230 \mathrm{~V} \mathrm{AC} \pm 15 \%$ supply voltage | 372332001 |
| Module for 2-pooint 3 -point and analogue activation; additional power $2 \mathrm{VA} ; 100 \mathrm{~V} \mathrm{AC} \pm 15 \%$ supply voltage | 372332002 |
| Aux. change-over contacts $12 \ldots 250 \mathrm{~V}$ ac; Infinitely variable, min. 100 mA and 12 V permissible load $6(2)$ a) | 372333001 |
| Aux. change-over contacts $12 \ldots 250 \mathrm{~V}$ ac; Gold plated, from 1 mA , to max. 30 V , wider range $3(1) \mathrm{a})$ | 372333002 |
| Potentiometer $2 \mathrm{k} \Omega 1 \mathrm{~W} 24 \mathrm{~V}$ | 372334001 |
| Potentiometer $130 \Omega 1 \mathrm{~W} 24 \mathrm{~V}$ | 372334002 |
| Potentiometer $1 \mathrm{k} \Omega 1 \mathrm{~W} 24 \mathrm{~V}$ | 372334006 |
| Adapter required when the temperature of the medium is $130 \ldots 180^{\circ} \mathrm{C}$ | 372336180 |
| Adapter required when the temperature of the medium is $180 \ldots 240^{\circ} \mathrm{C}$ | 372336240 |

ELECTRICAL CONNECTIONS


a) Using accessory type 372332 001. Same connections apply for the 100 V AC modules (type 372332002 ).
a) Using accessory type $12330201,372333002,372334001,372334002$ and 372334006 .
c) Accesssories type 3723336180 and 372336240 .
d) Accessory type 313529001 .


DIMENSIONS (mm)

| DIMENSIONS (mm) |  |  |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | A | B | C | D | $\varnothing \mathrm{E}$ | F | G | H | 1 | M | WEIGHT (kg) |
| AVM234S AVF234S | 230 | 314 | 90 | 72 | 40 | 57 | 18 | 37 | 18 | M10 | 4,1 |


| TYPE OF CHARACTERISTIC CURVES |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \text { Desired } \\ \text { character. } \\ \text { curve } \end{gathered}$ | Switch coding | Characteristic curve for valve | Characteristic curve for drive | Effective on valve |
|  |  |  | Signal |  |
| $\begin{aligned} & 0.0 \\ & 0 \\ & 0 \stackrel{0}{0} \\ & 0 \\ & 0 \\ & 0 \end{aligned}$ |  |  |  |  |
| $\stackrel{\text { ®. }}{\text { ¢ }}$ |  |  |  |  |
|  |  |  |  |  |
| $\stackrel{\text { ®. }}{\text { ¢ }}$ |  |  |  |  |
| Lim - factory setting |  |  |  |  |


| MOTOR RUNNING TIME SELECTION GUIDE |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Run time per mm | Switch coding | Run time for 14 mm stroke | Run time for 20 mm stroke | Run time for 40 mm stroke |
| 2s |  | $28 \mathrm{~s} \pm 1$ | $40 \mathrm{~s} \pm 1$ | $80 \mathrm{~s} \pm 4$ |
| 4 s |  | $56 \mathrm{~s} \pm 2$ | $80 \mathrm{~s} \pm 4$ | $160 \mathrm{~s} \pm 4$ |
| 6 s |  | $84 \mathrm{~s} \pm 4$ | $120 \mathrm{~s} \pm 4$ | $240 \mathrm{~s} \pm 8$ |
| = factory setting |  |  |  |  |

## ELECTRO-PNEUMATIC POSITIONERS PE986

## DESCRIPTION

The ADCATrol PE986 is an electro-pneumatic positioner used for direct operation of pneumatic linear or rotary actuators by means of lectrical controllers or control systems a 4 to $20 \mathrm{~mA}, 2$ to 10 V or split ranges output.
he which allows easy attachment of options such as limit switches, analog eedback modules, manifolds, volume boosters, amongst others.

MAIN FEATURES
Compact and flexible design.
Mounting onto any linear or rotary actuator.
Single or double acting.
Adjustable amplification and damping.
Independent adjustment of stroke range
ndependent adjustment of stroke range and zero position
ATEX approval (Ex ia).
OPTIONS AND ACCESSORIES
Module for analog position feedback.
Digital position feedback with inductive switches (two or three-wire ystem).
position feedback with microswitches.
Attachment kit for linear actuators acc. to IEC 534/NAMUR.
Attachment kit with rotary adaptor for rotary actuators acc. to VID/ ADE 3845.
Connection manifold with gauges.
ATEX approval (Ex d): Version PE983.
Volume boosters.


| AMBIENT CONDITIONS |  |
| :--- | :---: |
| Ambient temperature | $-40^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ |
| Relative humidity | Up to $100 \%$ |
| Operating conditions | According to IEC $654-1 ;$ <br> The device can be operated at a <br> Class D 2 location |
| Transport and storage <br> temperature | $-50^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ |
| Storage conditions | According to IEC $60721-3-1:$ <br> $1 \mathrm{~K} 5,1 \mathrm{~B} 1,1 \mathrm{C} 2,1 \mathrm{SS}, 1 \mathrm{M} 2$ |


| ELECTROMAGNETIC COMPATIBILITY (EMC) |  |
| :--- | :---: |
| Operating conditions | Industrial environment |
| Immunity | According to EN 61326 and EN 61000-6-2 |
| Emission | According to EN 61326, Class A and |
| Remark: NAMUR recommendation fulfilled $6100-6-3$ |  |


| CE MARKING |  |
| :--- | :---: |
| Electromagnetic <br> compatibility | 89/336/EWG |
| Low-voltage <br> regulation | 73/23/EWG not applicable |


| CAPACITY AT MAXIMUM DEVIATION (N/h) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| AIR PRESSURE SUPPLY | $\mathbf{1 , 4}$ bar | 2 bar | $\mathbf{4}$ bar | 6 bar |
| Without booster | 2700 | 3500 | 5500 | 7500 |
| With booster <br> LEXGG-FNGN | 18000 | 24000 | 40000 | 55000 |
| With booster <br> LEXG-HN | 38000 | 48000 | 80000 | 110000 |


| general |  |
| :---: | :---: |
| Material | Housing: Alluminium finished with DD-varnish black Mounting bracket: Alluminium Moving parts of feedback system: AISI 303 /1.4305 or AISI 316Ti / 1.4571 |
| IP rating | Protection class IP 54 (IP 65 on request) |
| Pneumatic connections | Female threaded ISO 228 G 1/8" |
| Electrical connections | M20 $\times 1,5$ Cable glands Screw terminals: max. $2.5 \mathrm{~mm}^{2}$ |
| Weight | Single acting: approx. $1,5 \mathrm{~kg}$ Double acting: approx. $1,8 \mathrm{~kg}$ Attachment kit: <br> For diaphragm actuators: approx. $0,3 \mathrm{~kg}$ For rotary actuators: approx. $0,5 \mathrm{~kg}$ |

## TECHNICAL DATA

|  | INPUT SIGNAL |
| :--- | :---: |
| Signal range | 4 to 20 mA or 2 to 10 V |
| Input resistance | $<200 \Omega$ at $20^{\circ} \mathrm{C}$ |
| Stroke range | 20 to $100 \%$ of the nominal operating range |
| Angular range | Linear: $30^{\circ}{ }^{\circ} \mathrm{to} 120^{\circ}$ <br> Equal percentage: $90^{\circ}$; from $70^{\circ}$ linear |


| OUTPUT SIGNAL |  |
| :--- | :---: |
| Output to actuator | 0 to $100 \%$ supply air pressure |


| AIR SUPPLY* |  |
| :---: | :---: |
| Air supply pressure | e 1,4 to 6 bar (20 to 90 psig) |
| Solid particle size and density | Class 2 |
| Oil rate | Class 3 |
| Pressure dew point | it 10 K below ambient temperature |
| * According to ISO 8573-1. <br> Remark: For air supply, we recommend the ADCA P10 filter regulator |  |
| AIR CONSUMPTION |  |
| Single acting | Air supply 1.4 bar (20 psig) $200 \mathrm{~N} / \mathrm{h}$ ( $7,1 \mathrm{scfh}$ ) |
|  | Air supply 3.0 bar ( 45 psig ) $400 \mathrm{~N} / \mathrm{h}(12,4 \mathrm{scfh})$ |
|  | Air supply $6.0 \mathrm{bar}(90 \mathrm{psig}) 600 \mathrm{~N} / \mathrm{h}(21,2 \mathrm{scfh})$ |
| Double acting | Air supply 1.4 bar ( 20 psig ) $350 \mathrm{~N} / \mathrm{h}$ ( $10,6 \mathrm{scfh}$ ) |
|  | Air supply $3.0 \mathrm{bar}(45 \mathrm{psig}) 550 \mathrm{~N} / \mathrm{h}(17,7 \mathrm{scfh})$ |
|  | Air supply 6.0 bar ( 90 psig) $750 \mathrm{~N} / \mathrm{h}(33,5 \mathrm{scfh})$ |


| AIR OUTPUT |
| :--- |
| $-3 \%$ for delivery flow $2350 \mathrm{~N} / \mathrm{h}(83 \mathrm{scff}$ sh) |
| $+3 \%$ for exhausted flow $1900 \mathrm{~N} / \mathrm{h}(67 \mathrm{scfh})$ |
| * Measured with air supply 1,4 bar and $50 \%$ of the signal range. |


| RESPONSE CHARACTERISTIC * |  |
| :--- | :---: |
| Amplification | Adjustable |
| Sensitivity | $<0,1 \%$ F.S. |
| Non-linearity (terminal <br> based adjustment) | $<1,0 \%$ F.S. |
| Hysteresis | $<0,3 \%$ F.S. |
| Supply air <br> dependency | $<0,3 \% / 0,1$ bar |
| Temperature effect | $<0,5 \% / 10 \mathrm{~K}$ |
| * Data based on the following parameters: stroke 30 mm , feedback |  |

* Data based on the following parameters: stroke 30 mm , feedb
lever 117.5 mm , max. amplification, air supply pressure 3 bar.


## OPTIONS AND ACCESSORIES

| INDUCTIVE LIMIT SWITCH (TWO-WIRE SYSTEM) |  |  |  | INDUCTIVE LIMIT SWITCH (THREE-WIRE SYSTEM) |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Input | Stroke / angle from actuator via positioner feedback lever |  |  | Input | Stroke / angle from actuator via positioner feedback lever |
| Output | 2 inductive proximity sensors acc. to DIN 19234 resp. NAMUR for connection to a switching amplifier with an intrinsically safe control circuit a) |  |  | Output | 2 inductive proximity sensors, three-wire system, LED indication, contact, pnp b) |
|  |  |  |  | Supply voltage Us | DC 10 to 30 V |
| $\begin{aligned} & \hline \begin{array}{l} \text { Current } \\ \text { consumption } \end{array} \\ & \hline \end{aligned}$ | Vane clear: > 3 mA Vane interposed: < 1 mA |  |  | Residual ripple <br> Switching | $10 \%$, US $=30 \mathrm{~V}$ |
| Supply voltage | DC 8 V , Ri approx. $1 \mathrm{k} \Omega$ |  |  | Switching frequency | 2 kHz |
| Residual ripple | < 5 \% |  |  | Constant | 100 m |
| Permissible <br> line resistance | < $100 \Omega$ |  |  | current | Gain: continuously adjustable from 1:1 to approx. 7:1 |
| Response characteristic b) | Gain: continuously adjustable from 1:1 to approx. 7:1 <br> Switching differential: <1 \% <br> Switching point repeatability: < 0,2 \% <br> EMC: according to EN 60 947-5-2 |  |  | characteristic <br> c) | Switching differential: < 1 \% Switching point repeatability: < $0.2 \%$ |
|  |  |  |  | b) Operating mode minimum ( $=$ low) / maximum ( $=$ high) selectable by adjustment of switch vanes; Contact closed within the positive range. c) For feedback lever effective length $117,5 \mathrm{~mm}(4,63 \mathrm{in})$, stroke 30 mm ( 1,28 in) and maximum gain. |  |
| a) For the standard version one switching amplifier is required. For the security version fail-safe amplifier for each inductive proximity sensor is required; Operating mode minimum (= low) / maximum (= high) selectable by adjustment of switch vanes; Operating mode normally closed circuit / normally open circuit selectable at switch amplifier output. <br> b) For feedback lever effective length $117,5 \mathrm{~mm}$ ( $4,63 \mathrm{in}$ ), stroke 30 mm ( 1,28 in) and maximum gain. |  |  |  |  |  |
|  |  |  |  | NECTION MANIFOLD WITH GAUGES |  |
|  |  |  |  | Indicating range | Stroke / angle from actuator via positioner feedback lever |
|  |  |  |  | Error limit | class 1.6 |
| MIT SWITCH ASSEMBLY WITH MICROSWITCHE |  |  |  | Pneumatic connections | Female threads Q1/4-18 NPT according to DIN 45141 |
| Input | Stroke / angle from actuator via positioner feedback |  |  |  |  |
| Output | 2 micro switches d) |  |  | ANALOG POSITION FEEDBACK |  |
|  | Switching capacity: max. 250 VA Switching voltage: max. 250 V <br> Switching current with ohmic resistance: max. 5 A Inductive resistance: max. 2A Bulb, metal filament: max. $0,5 \mathrm{~A}$ |  |  | nsor | Resistive precision conductive plastic element |
| load, alternating current |  |  |  | Input | Stroke/angle from actuator via position feedback lever; <br> Stroke range: 8 to 100 mm ( 0,3 to 4 in) Angular range: $60^{\circ}$ to $120^{\circ}$ |
| Connected load, direct current (refer to the following table) |  |  |  | Output | Two-wire system |
| Switching voltage, max. (V) |  | Ohmic load <br> (A) | Inductive load (A) <br> (A) | Permitted load | $\begin{gathered} \hline \mathrm{R}_{\text {Bax }}=(\mathrm{US}-12 \mathrm{~V}) / 0,02 \mathrm{~A} \\ (\mathrm{US}=\text { Supply voltage }) \end{gathered}$ |
| 30 |  | 5 | 3 |  | Supply voltage: DC 12 to 36 V |
| 50 |  | 1 | 1 | Power supply | Permitted ripple: < 10 \% p.p. <br> Supply voltage dependency: $<0,2 \%$ |
| 75 |  | 0,75 | 0,75 |  |  |
| 125 |  | 0,5 | 0,03 |  | Non-İinearity with terminal based seeting: $<1,0 \%$ F.S Hysterisis: $<0,5 \%$ F.S. |
| 250 |  | 0,25 | 0,03 |  | External resistance dependency: $<0,2 \% / R_{\mathrm{B}}$ max Temperature effect: $<0,3 \% / 10 \mathrm{~K}$ |
| $\begin{aligned} & \text { Response } \\ & \text { characteristic } \\ & \text { d) } \end{aligned}$ | Gain: continuously adjustable from 1:1 to approx. 7:1 Switching differential: < 2,5 \% Switching point repeatability: <0,2 \% |  |  | e) For feedback lever effective length $117,5 \mathrm{~mm}(4,63 \mathrm{in})$, stroke 30 mm ( 1,28 in) and maximum gain. |  |

## ELECTRO-PNEUMATIC POSITIONERS P1991

DESCRIPTION
The ADCATrol PI991 is a digital intelligent electronically configurable positioner with communication capabilities, designed for mounting to pneumatic linear or rotary actuators. Communication protocols communication, PROFIBUS PA and FOUNDATION Fieldbus-H1. The advanced diagnostic can be partially shown on the local LCD f the positioner or fully on a PC or a DCS workstation with a DTM of the positioner or fully on a PC or a DCS workstation with a DTM
based software (VALcare or Valve Monitor). The PI991 also has the capability to control a Partial Stroke Test (PST) ESD (Emergency Shut Down) valves.
MAIN FEATURES
Low operating cost.
Compact and flexible design
Easy to comission with user-friendly interface
Status and diagnostic messages displayed on LCD
Status and diagnostic messages displayed
Integrated mechanical position indicator.
Integrated mechanical position indicator.
Single or double acting
OPTIONS AND ACCESSORIES
HART, Profibus PA or FOUNDATION Fieldbus-H1 communication. SIL3 certification.
ATEX, FM, CSA and IECEx approvals.
Stainless Steel housing for Offshore or Food and Beverage applications.
Module for analog position feedback.
igital position feedback with inductive switches (two or three-wire system).
Digital position feedback with microswitches
ositioner with remote sensor.
Sensors for supply air pressure and output pressure
Attachment kit for linear actuators acc. to IEC 534/NAMUR and rotary actuators acc. to VDI/VDE 3845.
Connection manifold with gauges.
nfrared Interface for wir
Partial Stroke Test (PST) for Emergency Shut Down applications

| GENERAL |  |
| :--- | :---: |
| Material | Housing: AISI 316L / 1.4404 st. steel, $1,25 \mathrm{~mm}$ thick |
| IP rating | Protection Class IP 66 |
| NEMA 4X |  |


| AMBIENT CONDITIONS |  |
| :---: | :---: |
| Ambient temperature | $-40^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ |


| AIR SUPPLY |  |
| :--- | :---: |
| Air supply pressure | 1,4 to 6 bar $*$ |
| Supply air quality | According to ISO 8573-1 |
| Max. particle size <br> and density | Class 2 |
| Max. oil contents | Class 3 |
| 1,4 to 7 bar with spool valve. |  |


| HART COMMUNICATION (TWO-WIRE SYSTEM) |  |
| :--- | :---: |
| Reverse polarity <br> protection | built-in standard feature |
| Signal range | 4 to 20 mA |
| Operating range | 3.6 to 21 mA |
| Voltage | 12 to 36 VDC (unloaded circuit) |
| Maximum load | 420 Ohms ( 8.4 V at 20 mA$)$ |
| Communication signal | HART, 1200 Baud, FSK modulated on to |
| 20 mA |  |


| PROFIBUS-PA |  |
| :--- | :---: |
| Data transfer | acc. to PROFIBUS PA <br> profie class B based on EN <br> 50170 and DIN 19245 part 4 |


| FOXCOM COMMUNICATION (DIGITAL OPERATING MODE) |  |
| :--- | :---: |
| Input signal | digital |
| Supply voltage | 13 to 36 V DC |
| Supply current | $\sim 9 \mathrm{~mA}$ at 24 V DC |
| Communication signal | FoxCom digital, , 4800 Baud, FSK <br> modulated on supply Voltage |


|  | INPUT SIGNAL |
| :--- | :---: |
| Stroke range | 8 to 260 mm |
| Angular range | Up to $95^{\circ}$ |
| Remark: All "intelligent" versions are suplied with micro controller. |  |


| RESPONSE CHARACTERISTIC |  |
| :--- | :---: |
| Sensitivity | $<0,1 \%$ of travel span |
| Non-linearity (terminal <br> based adjustment) | $<0,4 \%$ of travel span |
| Hysteresis | $<0,3 \%$ of travel span |
| Suppla air <br> dependency | $<0,1 \% / 1$ bar |
| Temperature effect | $<0,3 \% / 10 \mathrm{~K}$ |
| Mechanical effect | 10 to 6 Oz up to $0,14 \mathrm{~mm}$, <br> 60 to 500 Hz up po $2 \mathrm{~g}:$ <br> $<0,25 \%$ of travel span |


| FIELDBUS COMMUNICATION (ACC. TO FISCO) |  |
| :--- | :---: |
| Input signal | digital fieldbus |
| Supply voltage | 9 to 32 V DC |
| Operating current | $10.5 \mathrm{~mA} \pm 0.5 \mathrm{~mA}$ (base current) |
| Current amplitude | $\pm 8 \mathrm{~mA}$ |
| Fault current | base current +0 mA <br> $(+4 \mathrm{~mA}$ by means of independent <br> FDE-safety circuit) |


| FOUNDATION FIELDBUS H1 |  |
| :--- | :---: |
| Data transfer | FF Specification Rev. 1.4, <br> Link-Master (LAS) |
| Function blocks | AO, PID, Transcucer, Resource, |
| $2 \times$ DI, DO |  |


| WITHOUT COMMUNICATION (4 TO 20 MA - TWO-WIRE SYSTEM) |  |
| :--- | :---: |
| Reverse polarity <br> protection | built--in standard feature |
| Signal range | 4 to 20 mA |
| Operating range | 3,8 to $21,5 \mathrm{~mA}$ |
| Voltage | DC 8 to $36 \mathrm{~V}($ unloaded circuit) $)$ |
| Maximum load | $300 \mathrm{Ohms}(6 \mathrm{~V}$ at 20 mA$)$ |

Remarks: For full product specifications, including requirements for use in potentially explosive atmospheres, different communication protocol (Profibus PA and FOUNDATION Fieldbus-H1) and others, please consult.

## ELECTRO-PNEUMATIC POSITIONERS TZIDC

DESCRIPTION
The ADCATrol TZIDC is a digital intelligent electronically configurable positioner with communication capabilities designed for mounting to neumatic linear or rotary actuators. It features a small and compact atio. ratio.
ully automatic determination of the control parameters and adaptation the final control element yield considerable time savings and an optimal control behaviour.
MAIN FEATURES
Low operating cost.
ompact and flexible design
Easy to comission with user-friendly interface.
ncreased shock and vibration resistance with gearless sensor activation.
Reliable and efficient, with integrated maintenance-friendly air filters. Automatic adjustment of control parameters during operation.
Integrated mechanical position indicator
Wide operating temperature range ( -40 to $+85^{\circ} \mathrm{C}$ ).
Mounting onto any linear or rotary actuator.
Single or double acting.
OPTIONS AND
ACCESSORIES: HART, Profibus PA or FOUNDATION Fieldbus-H1 communication.
ATEX, FM, CSA, GOST and IECEx approvals.
Module for anal
Modu for analog position feedback
Digital position feedback with inductive proximity
switches.
Digital position feedback with 24 V microswitches.
Positioner with remote sensor.
Attachment kit for linear actuators acc. to IEC 534/ NAMUR and rotary actuators acc. to VDI/VDE 3845.

Connection manifold with gauges
PC adapters for communication.
PC software for remote configuration and operation.


## DIMENSIONS (mm)



* Dimensions $A$ and $B$ are dependent on the rotary actuator.

TECHNICAL DATA

| GENERAL |  |
| :---: | :---: |
| Material | Aluminum with $\leq 0.1 \%$ copper |
| IP rating | Protection class IP 65 (IP 66 on request) NEMA 4 X |
| Surface | Electrostatic dipping varnish with epoxy resin, stove-hardened |
| Pneumatic connections | Female threaded ISO 228 G $1 / 4^{\prime \prime}$ |
| Electrical connections | M20 $\times 1,5$ Cable glands Screw terminals: max. $1.0 \mathrm{~mm}^{2}$ for options max. $2.5 \mathrm{~mm}^{2}$ for bus connector |
| Weight | $1,7 \mathrm{~kg}$ |
| Mounting orientation | Any |


| directives and communication |  |
| :---: | :---: |
| Directives | Compliant with: <br> - EMC directive 2004/108/EC from 12/2004 <br> - EC Directive for CE conformity marking |
| Communication | - HART ${ }^{\circledR}$ protocol 5.9 as standard, optionally HART ${ }^{\circledR}$ protocol 7.4 - Profibus PA <br> -FOUNDATION Fieldbus H1 <br> - Local connector for LCl (not in explosion protection area) <br> - HART communication via 20 mA signal line with (optional) FSK modem |


|  | TRAVEL |
| :---: | :---: |
| Rotation angle |  |
| Measuring range | $270^{\circ}$ |
| Working range (Fig.1) | Linear actuators: min. $25^{\circ}$, max. $45^{\circ}$ |
|  |  |
| Travel limit | Min. and max. limits, freely configurable between 0 to 100\% of total travel (min. range > 20\%) |
| Travel prolongation | $\begin{gathered} \text { Range of } 0 \text { to } 200 \mathrm{~s}, \\ \text { separately for each direction } \\ \hline \end{gathered}$ |
| Dead band time limit | Setting range of 0 to 200 s (monitoring parameter for control until the deviation reaches the dead band) |


| TRANSMISSION DATA AND CONTRIBUTING FACTORS |  |
| :---: | :---: |
|  | Output Y1 |
| Increasing | Increasing setpoint signal 0 to $100 \%$ Increasing pressure at output |
| Decreasing | Increasing setpoint signal 0 to $100 \%$ Decreasing pressure at output |
| Action (setpoint signal) |  |
| Increasing | Signal 4 to $20 \mathrm{~mA}=$ Position 0 to $100 \%$ |
| Decreasing | Signal 20 to 4 mA = Position 0 to 100\% |


| Characteristic curve (travel $=\mathrm{f}\{\text { setpoint signal\} })^{*}$ |  |  |
| :--- | :---: | :---: |
| Deviation | $\leq 0.5 \%$ |  |
| Tolerance band | 0,3 to $10 \%$, adjustable |  |
| Deaad band | 0,1 to $10 \%$, adjustable |  |
| Resolution <br> (ADD conversion) | $>16,000$ steps |  |

(A) Basic device

ELECTRICAL CONNECTIONS
Positioner / TZIDC control unit connections

(B) Options

| TERMINALS |  |
| :---: | :---: |
| TERMINAL | DESCRIPTION |
| +11/-12 | Analog input |
| +81/-82 | Binary input DI |
| +83/-84 | Binary output DO2 |
| +51/-52 | Digital feedback SW1 (optional module) |
| +41/-42 | Digital feedback SW2 (optional module) |
| +31/-32 | Analog feedback AO (optional module) |
| 1/2/3 | TZDIC remote sensor * |
| +51/-52 | Limit switch Limit 1 with proximity switch (optional) |
| +41/-42 L | Limit switch Limit 2 with proximity switch (optional) |
| 41/42/43 | Limit switch Limit 1 with microswitch (optional) |
| 51/52/53 | Limit switch Limit 2 with microswitch (optional) |
| * Only for options sensor. <br> Remarks: The TZ microswitches as variants. For the Sensor, the limit sw | TZIDC Remote Sensor or TZIDC for remote position <br> ZIDC can be fitted either with proximity switches or s limit switches. It is not possible to combine both version TZIDC Control Unit with TZIDC Remote switches are located in the TZIDC Remote Sensor. |
| BINARY OUTPUT DO* |  |
| Terminals | +83/-84 |
| Supply voltage | 5 to 11 V DC (Control circuit in accordance with DIN $19234 /$ NAMUR) |
| Output "logical 0" | $>0,35 \mathrm{~mA}$ to $<1,2 \mathrm{~mA}$ |
| Output "logical 1 " | $>2,1 \mathrm{~mA}$ |
| Direction of action | n Configurable "logical 0" or "logical 1" |

* Output configurable as alarm output by software.

C Connection TZIDC Remote Sensor / remote position sensor
(C) Connection TZIDC Remote Sensor /
(D) Limit value monitor with proximity switches or

| ANALOG INPUT SIGNAL |  |
| :--- | :---: |
| Set point signal (two-wire technology) |  |
| Terminals | $+11 /-12$ |
| Nominal operating <br> range | 4 to 20 mA |
| Split range config. | can be parameterized between 2 and $100 \%$ <br> of the nominal operating range |
| Operating range limits | 3.8 to 50 mA |
| Load voltage | 9.7 V at 20 mA |
| Impedance | $485 \Omega$ at 20 mA |


| DIGITAL INPUT |  |
| :---: | :---: |
| Function | - no function - move to $0 \%$ - move to $100 \%$ - hold previous position block local configuration - block local configuration and operation - block any access (local or via PC) |


| BINARY INPUT DI |  |
| :--- | :---: |
| erminals | $+81 /-82$ |
| Supply voltage | $24 \mathrm{VDC}(12$ to 30 V DC$)$ |
| Input "logical $0^{\prime \prime}$ | 0 to 55 V DC |
| Input "logical 1 " | 11 to 30 V DC |
| Input current | Maximum 4 mA |

## OPTIONAL MODULES

| MODULE FOR ANALOG FEEDBACK AO* |  | MODULE FOR DIGITAL FEEDBACK SW1, SW2 * |  |
| :---: | :---: | :---: | :---: |
| Terminals | +31/-32 | Terminals | +41/-42 and +51/-52 |
| Signal range | 4 to 20 mA (split ranges can be parameterized) | Supply voltage | 5 to 11 V DC (Control circuit in accordance with DIN 19234 / NAMUR) |
| Supply voltage (two-wire technology) | 24 V DC (11 to 30 V DC) | Output "logical 0" | $<1.2 \mathrm{~mA}$ |
| Characteristic curve | Rising or falling (configurable) | Output "logical 1 " | $>2.1 \mathrm{~mA}$ |
| Deviation | < $1 \%$ | Direction of action | "logical 0" or "logical 1" |
| Remarks: Without an "initializing", or in the $>20 \mathrm{~mA}$ (alarm level). | from the positioner (e.g. "no power", an error), the module sets the output to | Description | 2 software switches for binary position feedback (position adjustable within the range of 0 to $100 \%$, ranges cannot overlap). |

*The module for analog feedback and the module for digital feedback have separate slots and can be used together.
Assembly kits for limit monitor: Two proximity switches or microswitches for independent signaling of the actuator position, switching points are adjustable between 0 to $100 \%$

| LIMIT MONITOR WITH PROXIMITY SWITCHES 1, 2 |  |  |
| :---: | :---: | :---: |
| Terminals | +41/-42 and +51/-52 |  |
| Supply voltage | 5 to 11 V DC (Control circuit in accordance with DIN 19234 / NAMUR) |  |
| Direction of action | Metal tag in proximity switch | Metal tag outside proximity switch |
| e SJ2-SN | $<1.2 \mathrm{~mA}$ | $>2.1 \mathrm{~mA}$ |



TZIDC Remote sensor electrical connections

(A) Basic device
(1) Position sensor
(B) Options
(2) Limit monitor with proximity switches (optional)
(3) Limit monitor with microswitches (optional)

| TERMINALS |  |
| :---: | :---: |
| TERMINAL | DESCRIPTION / CONNECTION |
| $1 / 2 / 3$ | TZIDC control unit |
| $+51 /-52$ | Proximity switches Limit 1 (optional) |
| $+41 /-42$ | Proximity switches Limit 2 (optional) |
| $41 / 42 / 43$ | Microswitches Limit 1 (optional) |
| $51 / 52 / 53$ | Microswitches Limit 2 (optional) |
| Remarks: The TZIDC Remote Sensor can be fitted either with proximity |  |

Remarks: The TZIDC Remote Sensor can be fitted either with proximity
switches or microswitches as limit switches. It is not possible to combin both variants.

Remark: For full product specifications, including requirements for use in potentially explosive atmospheres, different communication protocols (Profibus PA and FOUNDATION Fieldbus-H1) and others, please consult.

## PNEUMATIC POSITIONERS PP981

## DESCRIPTION

The ADCATrol PP981 is a pneumatic positioner used for direct operation of pneumatic linear or rotary actuators by means of pneumatic controllers with a 0,2 to 1 bar proportional control signal. eosition feedback, and varies a pneumatic output signal to the ctuator accordingly, The actuator position is therefore guaranteed or any controller output signal and the effects of varying differential fessure. pressure
which allows easy attachment of options such as limit switches, analog feedback modules, manifolds, volume boosters, amongst others
MAIN FEATURES
Compact and flexible design
Mounting onto any linear or rotary actuator
Single or double acting.
Supply pressure up to 6 bar
Adjustable amplification and damping.
Independent adjustment of stroke range and zero position
Resistant to vibration effect in all directions.
ATEX approvals.
OPTIONS AND ACCESSORIES


Module for analog position feedback.
Digital position feedback with inductive switches (two or three-wire system).
Digital position feedback with microswitches.
Attachment kit for linear actuators acc. to IEC 534/NAMUR.
Attachment kit with rotary adaptor for rotary actuators acc. to VID/
VDE 3845.
Connection manifold with gauges.
Volume boosters.


TECHNICAL DATA
OPTIONS AND ACCESSORIES


| AMBIENT CONDITIONS |  |
| :--- | :---: |
| Ambient temperature | $-40^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ |
| Relative humidity | Up to $100 \%$ |
| Operating conditions | According to IEC $654-1 ;$ <br> The device can be operated at a <br> class D 2 location |
| Transport and storage <br> temperature | $-50^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ |


| RESPONSE CHARACTERISTIC * |  |
| :--- | :---: |
| Amplification | Adjustable |
| Sensitivity | $<0,1 \%$ F.S. |
| Non-linearity (terminal <br> based adjustment) | $<1,0 \%$ F.S. |
| Hysteresis | $<0,3 \%$ F.S. |
| Supply air <br> dependency | $<0,2 \% / 0,1$ bar |
| Temperature effect | $<0,3 \% / 10 \mathrm{~K}$ |
| * Data based on the following parameters: stroke 30 mm , feedback lever |  |

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| GAUGES |  |
| :--- | :--- |
| Indication range |  |
| Input | 0 to 1,6 bar |
| Output | 0 to 10 bar |
| Error limit | Class 1.6 |


| INPUT SIGNAL |  |
| :--- | :---: |
| Signal range | 0,2 to 1 bar or split range down to $\Delta \mathrm{w} 0,2$ bar |
| Stroke range | 8 to 100 mm |
| Angular range | Linear: $30^{\circ}$ 'o $120^{\circ}$ |


| OUTPUT SIGNAL |  |
| :--- | :---: |
| Output to actuator | 0 to $100 \%$ supply air pressure |


| AIR SUPPLY |  |
| :--- | :---: |
| Air supply pressure | 1,4 to 6 bar |
| Supply air | Free of oil, dust or water, <br> according to IEC $654-2$ |


| AIR CONSUMPTION |  |
| :--- | :---: |
| Single acting | With 1,4 bar air supply: $200 \mathrm{~N} / \mathrm{h}$ |
|  | With 3 bar air supply: $400 \mathrm{~N} / \mathrm{h}$ |
|  | With 6 bar air supply: $600 \mathrm{~N} / \mathrm{h}$ |
| Double acting | With 1,4 bar air supply: $350 \mathrm{~N} / \mathrm{h}$ |
|  | With 3 bar air supply: $550 \mathrm{~N} / \mathrm{h}$ |
|  | With 6 bar air supply: $750 \mathrm{~N} / \mathrm{h}$ |


| AIR OUTPUT |
| :--- |
| $-3 \%$ for delivery flow $2350 \mathrm{~N} / \mathrm{h}$ |
| $+3 \%$ for 2 exhausted flow $1900 \mathrm{~N} / \mathrm{h}$ |
| * Measured with air supply 1,4 bar and $50 \%$ of the signal range. |


| CAPACITY AT MAXIMUM DEVIATION (N/h/h) |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| AIR SUPPLY <br> PRESSURE | $\mathbf{1 , 4}$ bar | $\mathbf{2 ~ b a r}$ | $\mathbf{4}$ bar | $\mathbf{6}$ bar |
| Without booster | 2700 | 3500 | 5500 | 7500 |
| With booster <br> LEXG-FN/GN | 18000 | 24000 | 40000 | 55000 |
| With booster <br> LEXG-HN | 38000 | 48000 | 80000 | 110000 |



| INDUCTIVE LIMIT SWITCH (THREE-WIRE SYSTEM) |  |
| :--- | :---: |
| Input | Stroke / angle from actuator via positioner feedback |
| lever |  |$|$

maximum gain.

| ANALOG POSITION FEEDBACK |  |
| :---: | :---: |
| Sensor | Resistive precision conductive plastic element. |
| Input | Stroke/angle from actuator via position feedback lever; Stroke range: 15 to 80 mm (< 15 mm on request) Angular range: $60^{\circ}$ to $120^{\circ}$ |
| Output | Two-wire system; Signal range: 4 to 20 mA |
| Permitted load | $\mathrm{R}_{\text {Bmax }}=(\mathrm{US}-12 \mathrm{~V}) / 0,02 \mathrm{~A}$ <br> (US = Supply voltage) |
| Power supply | Supply voltage: DC 12 to 36 V Permitted ripple: < 10 \% p.p. Supply voltage dependency: $<0,2 \%$ |
| Response characteristic h) | Non-linearity with terminal based setting: $<1,0 \%$ F.S Hysterisis: < 0,5 \% F.S. External resistance dependency: $<0,2 \% / \Delta R_{\text {max }}$ Temperature effect: < $0,3 \% / 10 \mathrm{~K}$ |
| Explosion protection i) | Type of protection: II 2 G EEx ib/ia IIB/IIC T4/T6 Certificate of conformity: PTB 02 ATEX 2153 For operation in certified intrinsically safe circuits with the following maximum values: Umax: T4: 30 V ; T6: 22 V Imax: T4: 130 mA ; T6: 66 mA Pmax: T4: 0,9 W ; T6: 0,5 W Internal inductance: $9 \mu \mathrm{H}$ Internal capacitance to earth 10 nF or 6 nF differential |
| Ambient temperature | Temperature class T6: -40 to $40^{\circ} \mathrm{C}$ Temperature class T5: - 40 to $55^{\circ} \mathrm{C}$ Temperature class T : - -40 to $80^{\circ} \mathrm{C}$ |
| h) For feedback lever effective length of $117,5 \mathrm{~mm}$, stroke 30 mm and maximum gain. <br> i) National installation regulations must be observed; For retrofitting the product must be tested by a qualified inspector as a special version in accordance with ElexV. |  |


| COMMON DATA FOR OP |  |
| :---: | :---: |
| general |  |
| IP rating | Protection class IP 54; IP 65 on request |
| Mounting | Attachment to positioner |
| Electrical connections | Line entry: 1 or 2 cable glands M20 $\times 1,5$ <br> (others with Adapter AD-...) Cable diameter: 6 to 12 mm Screw terminals: max. 2.5 mm$^{2}$ (AWG14) |
| Materials | Base plate: galvanized steel Control vane: alluminium Setting mechanism: fibre glass-reinforced polyamide |


| CE MARKING |  |
| :--- | :---: |
| Electromagnetic <br> compatibility | 89/336/EWG <br> Low-voltage <br> regulation |


| SAFETY |  |
| :--- | :---: |
|  | safety class III; <br> Acc. to DIN EN <br> 61010-1 <br> (DIN IEC $61010-1)$ <br> (VDE |


| AMBIENT CONDITIONS |  |
| :--- | :---: |
| Ambient temperature <br> j) | -25 to $80^{\circ} \mathrm{C} ;$ <br> -40 to $80^{\circ} \mathrm{C}$ |
| Relative humidity | UU to $100 \%$ |
| Operating conditions | According to ICC $654-1 ;$ <br> The device can be operated at a <br> Class D 2 location |
| Transport and storage <br> temperate | $-40^{\circ} \mathrm{C}$ to $80^{\circ} \mathrm{C}$ |
| j) Withaut explosion protection; -40 <br> of inductive limit switch. $80^{\circ} \mathrm{C}$ for the fail-safe version |  |


| ELECTROMAGNETIC COMPATIBILITY (EMC) |  |
| :--- | :---: |
| Operating <br> conditions | Industrial environment |
| Immunity | Acc. to NAMUR recommendation NE21, <br> EN 61326 and EN 61000-6-2 |
| Emission | According to EN 5501, Group 1, Class A <br> and EN 61000-6-2 |

## ELECTRO-PNEUMATIC CONVERTERS PC25

DESCRIPTION
The ADCATrol PC25 is a compact device which converts a standard analog signal to a standard pneumatic signal, for the change-over etween electrical controllers to pneumatic control valves, or from ectrical measuring systems to pneumatic controliers Putisal a 4 to 20 mA nput signal into a proportional linear 0,2 to 1 bar output signal, with a respective supply pressure of 1,7 to 5 bar.

MAIN FEATURES
Particularly compact design
Good dynamic response.
mmune to mechanic vibrations.
ow maintenance and low consumption.
High reliability.
Adjustable output measuring span
OPTIONS: $\quad$ Pressure gauge on body.
AVAILABLE $\quad$ Other output pressure ranges
MODELS:
PC25.
SIZES: $\quad 1 / 4^{\prime \prime}$.
CONNECTIONS: Female threaded NPT.
INSTALLATION: In any position.
See IMI - Installation and maintenance
instructions.

TECHNICAL DATA

| GENERAL |  |
| :--- | :---: |
| Peerating temperature | -40 to $+85^{\circ} \mathrm{C}$ |
| IP rating | IP 65 |
| Electric connections | DIN 43650, form A |
| Pneumatic connections | Female threaded $1 / 4$ " NPT |
| Material | Passivated zinc die-casting epoxy painted, <br> NBR diaphragms, <br> Glass reinforced PA cover. |
| Operating position | Any |
| Weight | 1 kg |


| AIR SUPPLY* |  |
| :--- | :---: |
| Purity | Max. particle size $5 \mu \mathrm{~m}$ <br> Max. particle density: $5 \mathrm{mg} / \mathrm{m}^{3}$ |
| Oil content | Max. concentration: $1 \mathrm{mg} / \mathrm{m}^{3}$ |$|$| 1,7 to 5 bar |
| :--- |
| Supply pressure ** |

* Free of oill, water and dust, according to DIN/ISO $8573-1$
** Do not exceed the maximum operating pressure of the actuator!

| PNUEMATIC OUTPUT SIGNAL |  |
| :--- | :---: |
| Output pressure | 0,2 to 1 bar (others on request) |
| Flow capacity | $>300 \mathrm{~N} / /$ min, forward $\&$ relief |
| Linearity | $\leq 0,5 \%$ of span |
| Hysteresis | $\leq 0,5 \%$ of span |
| Response time | $<0,5$ seconds for a a to to $0 \%$ or 9 o to $10 \%$ <br> of output pressure into 10 acc load |
| Supply sensitivity | $<0,075 \%$ span output change per $\%$ supply <br> pressure change |

DIMENSIONS (mm)


CALIBRATION
When the instrument is first installed or after a long downtime period, a moderate zero shift is normal. This is due to the rubber diaphragms which are stretched by the internal springs. After a few operations, the instrument will settle into its normal operating condition. In these circumstances, the instrument should be put to work by alternately applying zero and full scale signals several times. Zero calibration should then be carried out.
Adjust zero control $n^{\circ} 2$ (anti-clockwise) to give minimum required output pressure.
Adjust range control $\mathrm{n}^{\circ} 3$ (anti-clockwise) to give maximum required output pressure.
Note: Reverse acting operation.
About 20 turns of the zero screw may be required to reset the zero point.
TYPICAL INSTALLATION


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## AIR FILTER REGULATOR <br> P10

## DESCRIPTION

The P10 air filter regulators are used to remove both solid and liquid impurities from the air and to regulate the output pressure to the required value for general purpose pneumatic systems
The filter bowl is transparent, allowing easy monitoring of the condensate level.

MAIN FEATURES
Self relieving.
Compact combined filter/regulator
micron large surface area element
Manual and automatic condensate exhaustion are easier when there is no pressure.
Pressure gauge D. $42 \times 1 / 8^{\prime \prime}$
Mounting bracket.
USE:
Pneumatic systems
AVAILABLE
MODELS:
P10 - alluminium and polycarbonate.
SIZE AND
CONNECTION:
Female threaded ISO 7 Rp 1/4

| LIMITING CONDITIONS |  |
| :--- | :---: |
| Valve model | P10 |
| Maximum upstream pressure | 12 bar |
| Maximum downstream pressure | 10 bar |
| Minimum downstream pressure | 0,5 bar |
| Maximum design temperature | $60^{\circ} \mathrm{C}$ |
| Minimum operating temperature | $-10^{\circ} \mathrm{C}$ |


| MATERIALS |  |
| :---: | :---: |
| POS. <br> No | DESIGNATION |
| 1 | Filtering element |
| 2 | Bowl (with bowl guard included) |
| 5 | Exhaust ring |
| 6 | Air inet connection |
| 7 | Low pressure air outlet |
| 8 | Flow indicator arrow |
| 11 | Pressure regulating knob |
| 13 | Pressure gauge |

VALSTEAM JDC」

## UNIVERSAL PROCESS CONTROLLERS UC－820

## DESCRIPTION

The ADCATrol UC－820 is a digital universal controller used in the automation of industrial processes．It is ideally suited for use with our range of instrumentation，electric and pneumatic control valves and electrical equipmen
號 hermocouple（TC），logic（binary）and analog inputs．The controller has options for relay，open－collector（OC）and analog outputs using he innovative SMART PID algorithm

MAIN FEATURES
Universal measuring input：Resistance thermometer（RTD），

Set point value：constant，programmed or from the additional analog put．
n／off，PID，PID three－step and two－step control（valve control）or PID of heating－cooling type．
2 NO relay alarm outputs and 2 other outputs of choice between relay， OC or analog outputs（ $0 / 4$ to 20 mA or 0 to 10 V ）．
Binary input control．
Soft－start function．
8 types of alarm functions．
24 V DC supply output to power transmitters and others．
＂Gaignal retransmission．
＂Gain scheduling＂and timer functions．
Auto－tuning using the smart PID algorithm．
Galvanically isolated inputs and outputs．
Password protection．
Fully programmable from the front panel．
S－485 Modbus RTU communication． IP rating IP 65 ．

AVAILABLE
MODELS：

## UC－820．




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| DIMENSIONS（mm） |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | A | B | C | D | E | F | WEIGHT（kg） |
| UC－820 | 48 | 96 | 93 | 70 | 8 | 15 | 0,2 |



| OTHER CONNECTIONS |  |
| :---: | :---: |
| POWER SUPPLY | ADDITIONAL ANALOG INPUT SIGNAL |
| $\begin{array}{\|l\|} \hline 17- \\ 18- \end{array} \text { supply }$ | $104.20 \mathrm{~mA} \stackrel{-}{+}^{6}$ |
| BINARY INPUT 1 AND 2 | CURRENT TRANSFORMER INPUT |
| $+$13 11 <br> 12 10 <br> OU2 OU1  |  |
| RS-485 INTERFACE | 24 V TRANSDUCER SUPPLY |
| $\begin{array}{l\|l\|} \mathrm{B}(-) & 16 \\ \mathrm{RS}-485 & 15 \\ \hline \mathrm{~A}(+) & 15 \\ \hline \end{array}$ | $26_{+}^{-}$ |



## UNIVERSAL DISPLAY

 UD-720
## DESCRIPTION

The ADCATrol UD-720 is a programmable digital panel display used for the measurement of standard sensor and analog signals applied in atomation. It is ideally suted for use with our range of instrumentation uch as pressure V unit features a 24 V DC supply output for transmitters.

MAIN FEATURES
Easy to comission with user-friendly interface
Measuring inputs for resistance thermometer (RTD), thermocouples (TC), 0 (4) to $20 \mathrm{~mA}, 0$ to $10 \mathrm{~V}, 0$ to 60 mV and resistance ( $\Omega$ ).
2 NO relay alarm outputs.
24 V DC supply output to power transmitters and others.
Three color display ( 14 mm high) with programmable color settings hree color display ( 14 mm hin
21-point individual characteristic function for input rescaling and conversion.
Galvanically isolated inputs and outputs
Fully programmable from the front panel.
Password protection.
IP rating IP 65.
OPTIONS:
Change-over relay alarm outputs.
$0(4)$ to 20 mA and 0 to 10 V outputs for retransmission of any of the measured inputs RS-485 Modbus RTU communication.
AVAllABLE
MODELS:
UD-720


| DIMENSIONS (mm) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MODEL | A | B | C | D | WEIGHT (kg) |
| UD-720 | 96 | 48 | 67 | 93 | 0,2 |



| GENERAL |  |
| :--- | :---: |
| Supply voltage | 85 to $253 \mathrm{VAC/DC}$ or |
| 20 to $40 \mathrm{VAC/DC}$ |  |$|$| Ambient temperature | -25 to $+55^{\circ} \mathrm{C}$ |
| :--- | :---: |
| Storage temperature | -30 to $+70^{\circ} \mathrm{C}$ |
| IP rating | IP 65 (front) ; IP 10 (rear) |
| Material | Housing in PC/ABS |
| Humidity | $<85 \%$ without condensation |
| Front panel | $96 \times 48 \mathrm{~mm}$ (cutout: $92 \times 45 \mathrm{~mm}$ ) |
| Operating position | $\quad$ Any |
| External magnetic field | 0 to $400 \mathrm{~A} / \mathrm{m}$ |

OUTPUTS

| OUTPUTs |  |
| :--- | :---: |
| Relay | 2 NO volt free contacts, $0,5 \mathrm{~A} @ 250 \mathrm{VAC}$ |
|  | 2 change-over volt free eontacts |
|  | $0.5 \mathrm{~A} @ 23 \mathrm{~V} \mathrm{AC}$ |
| OC open-collector | Passive NPN, $30 \mathrm{~mA} @ 30 \mathrm{~V} \mathrm{DC}$ |
| Continuous voltage | 0 to $10 \mathrm{~V}, 500 \Omega$ min. |
| Continuous current | $0(4)$ to $20 \mathrm{~mA}, 500 \Omega$ max. |
| Transducer supply | $24 \mathrm{~V} \mathrm{DC}, 30 \mathrm{~mA}$ max. |


| DIGITAL INTERFACE |  |
| :--- | :---: |
| Interface type | RS-485 |
| Protocol | Modbus RTU 8N2, 8E1, 801, 8N1 |
| Baud rate | $4.8,9.6,19.2,38.4,57.6,115.2$ kbit/s |


|  | INPUTS * |
| :--- | :--- |
| PT100 | -200 to $850^{\circ} \mathrm{C}$ |
| PT500 | -200 to $850^{\circ} \mathrm{C}$ |
| PT1000 | -200 to $850^{\circ} \mathrm{C}$ |
| Fe-CuNi $(\mathrm{J})$ | -100 to $1200^{\circ} \mathrm{C}$ |
| NiCr-NiAl $(\mathrm{K})$ | -100 to $1372^{\circ} \mathrm{C}$ |
| PtRh10-Pt (S) | 0 to $1767^{\circ} \mathrm{C}$ |
| PtRh13-Pt $(\mathrm{R})$ | 0 to $1767^{\circ} \mathrm{C}$ |
| NiCr-CuNi $(\mathrm{E})$ | -100 to $1000^{\circ} \mathrm{C}$ |
| NiCrSi-NiSi $(\mathrm{N})$ | -100 to $1300^{\circ} \mathrm{C}$ |
| Current input $(\mathrm{I})$ | -20 to 20 mA |
| Voltage input $(\mathrm{U})$ | -10 to 10 V |
| mV input $(\mathrm{mV})$ | 0 to 60 mV |

Adastitonal errors:
compensation of the reference junction temperature: $\leq 1^{\circ} \mathrm{C}$
Due to automatic compensation of the cable resistance for $R T D s: \leq 0.5^{\circ} \mathrm{C}$.
Due to automatic compensation of the cables for resistance measurement: $\leq 0.2$
$\Omega$.
From temperature changes: $100 \%$ of the class $/ 10 \mathrm{~K}$

| SAFETY AND COMPATIIILITY REQUIREMENTS |  |
| :---: | :---: |
| Electromagnetic compatibility | Noise immunity acc. to EN 61000-6-2 |
|  | Noise emissions acc. to EN 61000-6-4 |
| Pollution level | Level 2 acc. to EN 61010-1 |
| Installation category | Cat. III acc. to EN 61010-1 |
| Maximal phase-to-earth operating voltage | Supply circuit: 300 V ; Remaining circuits: 50 V acc. to EN 61010-1 |




